

Specifying And Measuring Spherical Surface Irregularity[©]

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This paper will define surface irregularity for spherical surfaces, offer information on measurement methods for testing surface irregularities, and some specification guidelines.

SURFACE IRREGULARITY FOR SPHERICAL SURFACES

Irregularity is error in surface form relative to an ideal form. For spherical surfaces, irregularity is how much the actual surface deviates from the radius of curvature of an ideal or perfect best fit sphere (BFS), and accordingly may be called asphericity¹. BFS is chosen at minimum Root Mean Square (RMS) irregularity². Figure 1 shows a 2-D example of the relationship between ideal form and the actual surface.



Figure 1 - Ideal Form and Actual Surface

Typically, irregularity is represented as form error. Differences between the actual and ideal surface positions are plotted relative to a horizontal line representing an ideal surface³. Figure 2 shows the information presented in Figure 1 in this form error convention.



Figure 2 - Representation of Form Error

MEASUREMENT METHODS FOR TESTING SURFACE IRREGULARITIES

Traditional Method - Test Plate

The traditional tool for form measurement of spherical and flat optical surfaces was the test plate⁴. Bringing the test plate and the surface under test into close contact formed interference fringes known as Newton Rings. The quantity and nature of these fringes indicated the form accuracy of the surface under test relative to the test plate, and what was seen using a test plate was a combined power and irregularity⁵. Radius and irregularity were appraised using the test plate using fringe counting⁶.

With test plate based metrology, power was held in proportion to allowable irregularity. Power masks irregularity⁷, and to guarantee irregularity detection the power tolerance (\sim 4x specified irregularity⁸) was



have been kept smaller than required for the desired optical performance.

Current Methods – Non-Contact Interferometric Testing

Non-Contact interferometers like a Fizeau or Twyman-Green use laser light to illuminate a surface under test. Interference between the reflected wavefront and the reference wavefront forms a fringe pattern. This isn't much different than traditional testplating under a monochromatic light source, except the part and reference are not brought into contact. Interferometers are found in most shops, often located directly in the manufacturing area.

Interferometers combined with a 5-axis mount tied to a radius rail or a distance measuring interferometers (DMIs) allow accurate positioning of the part at an approximate null position, and power can be separated from irregularity⁹. During the test, the fringe pattern is analyzed using fringe analysis software, and the errors present can be apportioned based on errors in null position (power) and errors present in the surface under test (irregularity)¹⁰.

Test results are shown in a 3-D representation, with the Z-axis representing the axis of the measuring instrument¹¹. Different heights are represented by different colors or, in a one color plot, as different shades. The 2-D information in Figure 3 can be transformed into the 3-D plot Figure 4 shows.



Figure 3 – 2 Dimensional Form Error Data

Figure 4 – 3 Dimensional Form Error Data

The data generated can be handled using standard statistical functions, typically calculating a Peak-To-Valley (P-V) and RMS value for irregularity¹². Calculations are preformed over a specific area¹³, usually equal to or larger than the clear aperture.

SPECIFICATION GUIDELINES

Peak-To-Valley error is still the primary quantity specified for irregularity or asphericity. There are practical reasons for this. An optician using test plating can only assess PV error. Additionally, the contributors to PV can be targeted directly during the polishing process.

For many applications PV alone is not enough ¹⁴. Depending on the testing options available for the surface to be made, the items that can be specified can change. If the spherical surface has good coverage on an interferometer and the fringe analysis software supports quantification, virtually any means of specifying asphericity can be used.

CONCLUSIONS

- Irregularity is error in surface form relative to an ideal form
- Irregularity is graphically expressed as form error relative to a horizontal line (2-D) or plane (3-D) representing an ideal surface
- Irregularity is measured using interferometry, with qualitative fringe interpretation during test plating or electronic analysis of fringe pattern in non-contact interferometry



• Specify irregularity tolerances relative to capabilities of planned testing

- ¹³ MetroPro Reference Guide OMP-0347J, Page 5-1, Zygo Corporation, Middlefield, Connecticut, 2004
- ¹⁴ R.E. Fischer, B. Tadic-Galeb, P. Yoder, *Optical System Design*, Pg 376 379, McGraw Hill, New York City, 2008

¹ W. Smith, *Modern Lens Design*, Pg 574, McGraw Hill, New York City, 2005

² T. L. Schmitz et al, "Uncertainties in interferometric measurements of radius of curvature", *Optical Manufacturing and Testing IV*, H. Philip Stahl editor, Vol. 4451, 432-447, SPIE, Bellingham, WA, 2001

³ H.H. Karow, Fabrication Methods For Precision Optics, Pg 670, John Wiley & Sons, New York City, 1993

⁴ H.H. Karow, *Fabrication methods for precision optics*, Ch 6.1, John Wiley & Sons, New York City, 1993

⁵ Ibid, Pg 642

⁶ Ibid, Pg 641 - 642

⁷ W.J. Smith, *Modern Lens Design*, Pg 574, McGraw Hill, New York City, 2005

⁸ H.H. Karow, Fabrication methods for precision optics, Pg 641, John Wiley & Sons, New York City, 1993

⁹ Ibid, Pg 662

¹⁰ Ibid

¹¹ MetroPro Reference Guide OMP-0347J, Page 7-1, Zygo Corporation, Middlefield, Connecticut, 2004

¹² H.H. Karow, Fabrication methods for precision optics, Pg 670, John Wiley & Sons, New York City, 1993